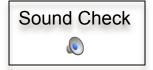
# An Efficient Posterior Regularized Latent Variable Model for Interactive Sound Source Separation



Nicholas J. Bryan, Stanford University Gautham J. Mysore, Adobe Research

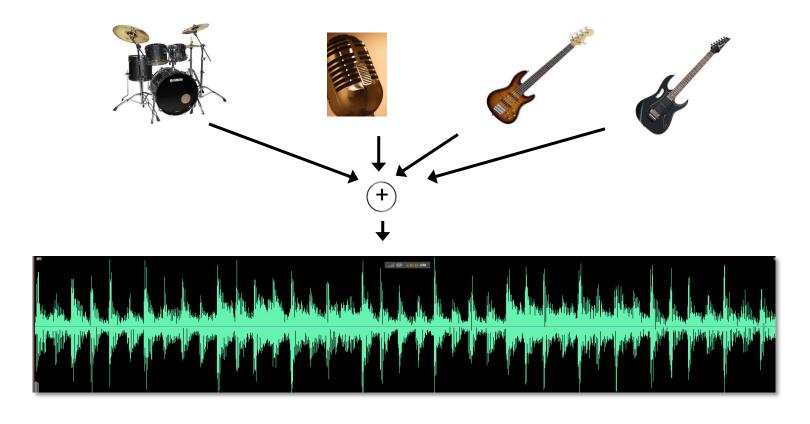


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## **Motivation I**

Real world sounds are mixtures of many individual sounds



#### Current State-of-the-Art

Non-negative matrix factorization (NMF)
 [Lee & Seung, 2001; Smaragdis & Brown 2003]

Related latent variable models (LVM)
 [Raj & Smaragdis 2005, Smaragdis et al., 2006]

#### Latent Variable Model

Probabilistic latent component analysis (PLCA) [Smaragdis et al., 2006]

$$\mathbf{X} \approx P(f,t) = \sum_{z} P(z) P(f|z) P(t|z)$$

$$P(f|z)$$

$$P(z)$$

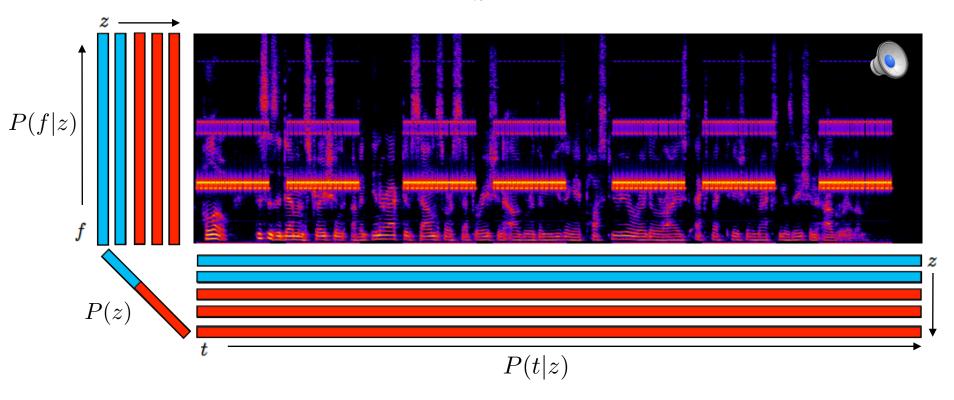
P(f|z) Basis vectors, frequency components, dictionary

P(z) Latent component weights

P(t|z) Time activations or gains

## Latent Variable Model

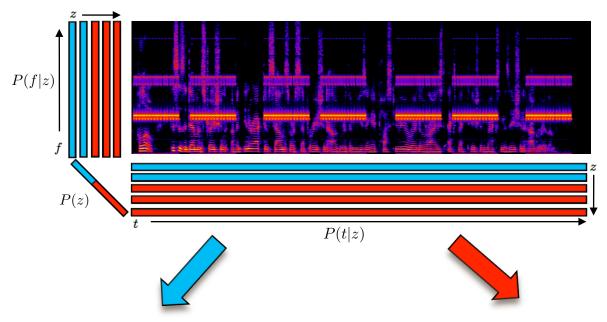
$$\mathbf{X} \approx P(f,t) = \sum_{z} P(z) P(f|z) P(t|z)$$

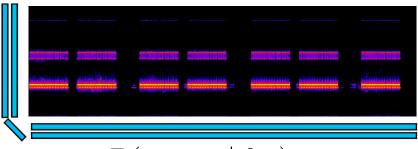


Solve via an expectation-maximization (EM) algorithm

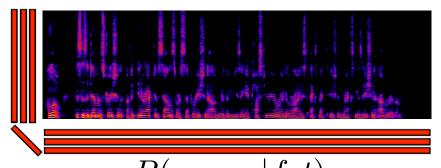
## Latent Variable Model

$$\mathbf{X} \approx P(f,t) = \sum_{z} P(z) P(f|z) P(t|z)$$





$$P(s=s_1|f,t)$$



$$P(s = s_2|f, t)$$

#### **Problems**

Requires isolated training data (supervised/semi-supervised)

Don't incorporate auditory/perceptual models of hearing

One-shot process, cannot correct for poor results

Very difficult, underdetermined problem

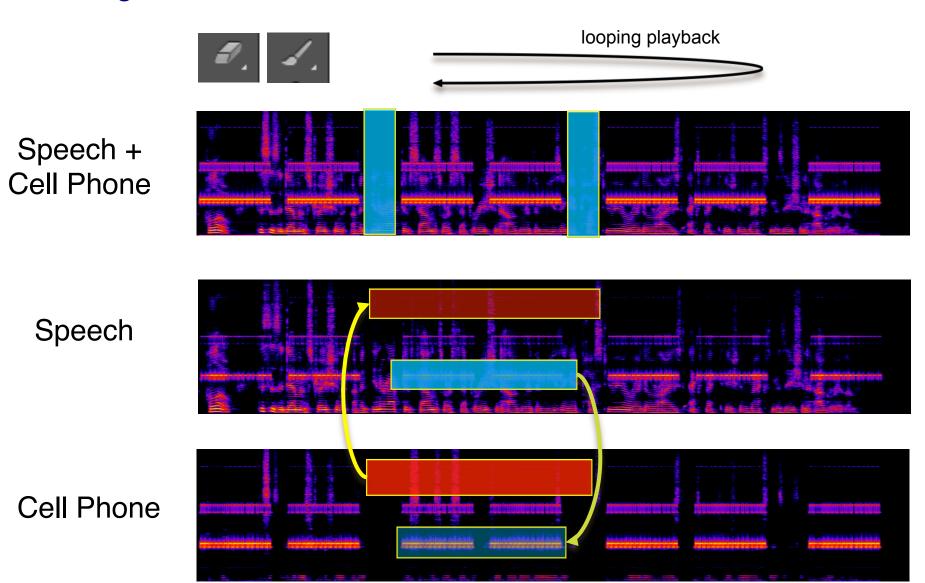
### Focus

Eliminate the need to explicit training data

Method of user feedback to guide separation

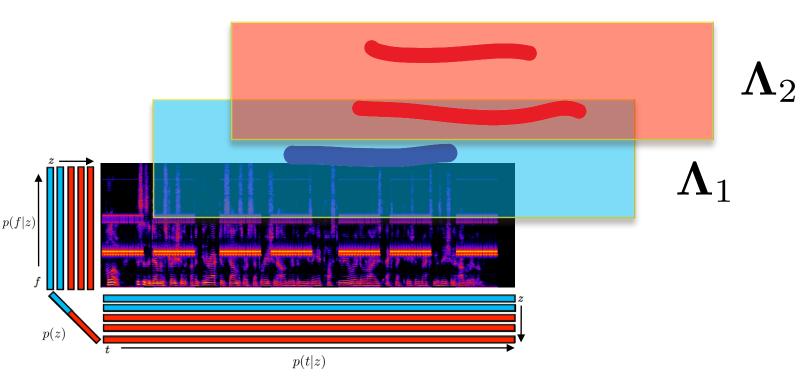
Algorithm to incorporate the user feedback

# Paradigm: Listen, Paint, Remove



## Latent Variable Model w/Painting Constraints

$$\tilde{P}(f,t) = \sum_{z} \tilde{P}(z)\tilde{P}(f|z)\tilde{P}(t|z)$$



Incorporate painting annotations into the model

#### **Constraints**

Constraints typical encoded as:

$$P(f|z) \quad P(t|z) \quad P(z)$$

- Prior probabilities on model parameters
- Direct observations
- Does not (reasonably) allow time-frequency constraints
- Posterior regularization [Graça et al., 2007, 2009]
  - Complementary method that allows time-frequency constraints P(z|f,t)
  - Iterative optimization procedure for each E step
  - Well suited for our problem

## **Expectation Maximization**

$$\ln P(\mathbf{X}|\mathbf{\Theta}) = \mathcal{F}(Q,\mathbf{\Theta}) + \mathrm{KL}(Q||P)$$
$$\ln P(\mathbf{X}|\mathbf{\Theta}) \ge \mathcal{F}(Q,\mathbf{\Theta})$$

E Step: 
$$Q^{n+1} = \underset{Q}{\operatorname{arg\,max}} \mathcal{F}(Q, \mathbf{\Theta}^n)$$
$$= \underset{Q}{\operatorname{arg\,min}} \operatorname{KL}(Q||P)$$

M Step: 
$$\mathbf{\Theta}^{n+1} = \underset{\mathbf{\Theta}}{\operatorname{arg max}} \mathcal{F}(Q^{n+1}, \mathbf{\Theta})$$

# **Expectation Maximization w/Posterior Constraints I**

$$\ln P(\mathbf{X}|\mathbf{\Theta}) = \mathcal{F}(Q,\mathbf{\Theta}) + \mathrm{KL}(Q||P)$$
$$\ln P(\mathbf{X}|\mathbf{\Theta}) \ge \mathcal{F}(Q,\mathbf{\Theta})$$

E Step: 
$$Q^{n+1} = \underset{Q \in \mathcal{Q}}{\operatorname{arg max}} \mathcal{F}(Q, \mathbf{\Theta}^n)$$
$$= \underset{Q \in \mathcal{Q}}{\operatorname{arg min}} \operatorname{KL}(Q||P)$$

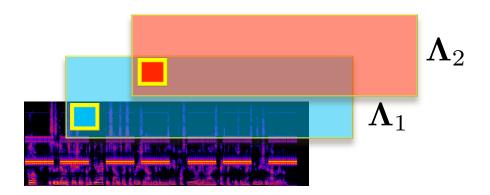
M Step: 
$$\mathbf{\Theta}^{n+1} = \underset{\mathbf{\Theta}}{\operatorname{arg max}} \mathcal{F}(Q^{n+1}, \mathbf{\Theta})$$

# **Linear Grouping Expectation Constraints**

$$\underset{Q \in \mathcal{Q}}{\operatorname{arg \, min}} \ \operatorname{KL}(\ Q(z|f,t) \mid\mid P(z|f,t) \ )$$

• For each time-frequency point of P(z|f,t), solve

$$\begin{array}{ll}
\operatorname{arg\,min} & -\mathbf{q}^{\mathrm{T}} \ln \mathbf{p} + \mathbf{q}^{\mathrm{T}} \ln \mathbf{q} \\
\operatorname{subject\ to} & \mathbf{q}^{\mathrm{T}} \mathbf{1} = 1, \ \mathbf{q} \succeq 0
\end{array}$$



$$\lambda^{\mathrm{T}} = \left[ \mathbf{\Lambda}_{1_{ft}} \, \mathbf{\Lambda}_{1_{ft}} \, \mathbf{\Lambda}_{1_{ft}} \, \ldots \mathbf{\Lambda}_{2_{ft}} \, \mathbf{\Lambda}_{2_{ft}} \, \mathbf{\Lambda}_{2_{ft}} \right]$$

# Fast Updates

With simple penalty, both E and M steps are in closed form

Reduces to simple, fast multiplicative updates vs. NMF

Roughly the same computational cost as without constraints

expectation step for all 
$$z, f, t$$
 do 
$$Q(z|f, t) \leftarrow \frac{P(z)P(f|z)P(t|z)}{\sum_{z'} P(z')P(f|z')P(t|z')} \qquad Q(z|f, t) \leftarrow \frac{P(z)P(f|z)P(t|z)}{\sum_{z'} P(z')P(f|z')P(t|z')}$$
 end for end for

#### **Evaluation**

- BSS-EVAL metrics [Vincent et al., 2006]
  - Signal-to-Distortion Ratio (SDR)
  - Signal-to-Interference Ratio (SIR)
  - Signal-to-Artifact Ratio (SAR)

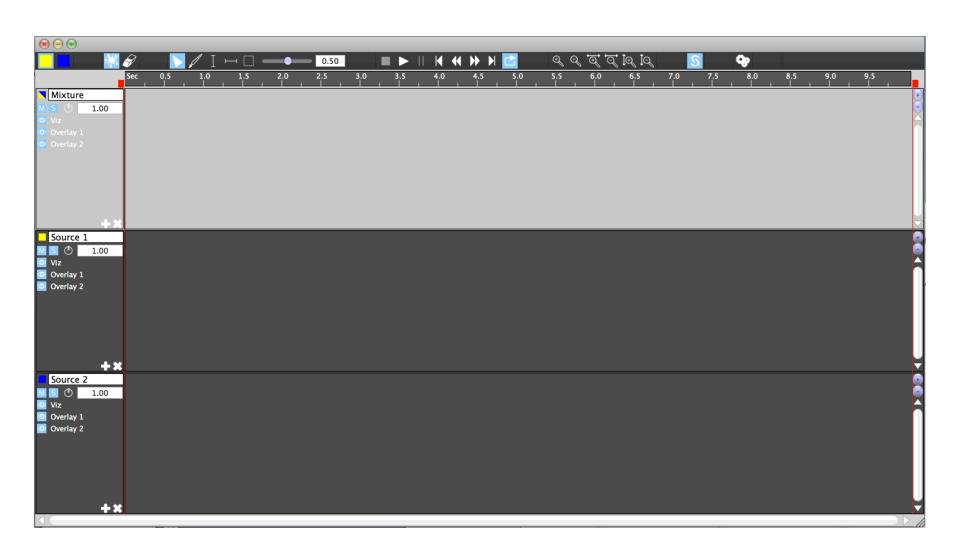
#### Test material

- Cell phone + speech (C), drums + bass (D), orchestra + cough (O), piano + wrong note (P), siren + speech (S)
- Vocals + background music (S1, S2, S3, S4)

#### Results

- Outperformed prior state-of-the-art on tested material
- Outperformed SiSEC 2011 vocals + background music winner

## **Live Demonstration**



## **Jackson 5 Remix**



Jackson 5's "I want You Back"



Cher Llyod's "Want U Back"



Remix

## A Look Back

Perceptual domain, objective evaluation is difficult

Human evaluation within the learning process

Processing training data only

#### Conclusion

- Sound source separation algorithm
  - Time-frequency constraints via posterior regularization
  - No explicit training data
  - Efficient, interactive algorithm w/closed-form update equations
  - Improved separation quality over prior work
  - Open source software
- Poster ID: 348
- Demos at ccrma.stanford.edu/~njb/research/iss

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